

### **scalable planning concurrent action pdf**

planning domains. Furthermore, we remark that Tensorflow is highly scalable, converging to a strong plan on a large-scale concurrent domain with a total of 576,000 continuous action parameters distributed over a horizon of 96 time steps and 100 parallel instances in only 4 minutes. We provide a number of insights that

### **Scalable Planning with Tensorflow for Hybrid Nonlinear Domains**

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A new graphical representation called ScalPL (Scalable Planning Language) is then introduced for building even complex concurrent activities of all kinds from those elemental activities, one mind-sized bite at a time.

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enced (positively or negatively) by the concurrent performance of other actions (or exogenous events for that matter); (2) The planning problem: how do we plan for multiple agents using such a representation. In this paper, we show how the STRIPS action representation can be augmented to handle concurrent interacting ac-

### **Planning with Concurrent Interacting Actions**

Permanency action through concurrent planning The introduction of legislation in favour of 'permanency planning', in 1980, led to a marked decline in the number of North American children entering the public care system for much of that decade. In recent years, however, the number of children in care in the USA has been steadily rising.

### **Permanency Action through Concurrent Planning**

Furthermore, we remark that Tensorflow is highly scalable, converging to a strong plan on a large-scale concurrent domain with a total of 576,000 continuous action parameters distributed over a horizon of 96 time steps and 100 parallel instances in only 4 minutes.

### **[1704.07511] Scalable Planning with Tensorflow for Hybrid**

Temporal Multiagent Planning with Concurrent Action Constraints Matthew Crosby and Ronald P. A. Petrick School of Informatics University of Edinburgh Edinburgh EH8 9AB, Scotland, UK m.crosby@ed.ac.uk, rpetrick@inf.ed.ac.uk Abstract This paper investigates how centralised, cooperative, multi-agent planning problems with concurrent action constraints

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